



# Trajectory Calculation as Supporting Tool for Dust Storm Forecasting

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# Outline

- ☐ Introduction
- ☐ Dust forecasting
- ☐ Methodology
- ☐ Proposed system
- ☐ System validation
- ☐ Conclusions



# Introduction


- **Dust storms affect human**
  - Health
  - Commercial
  - Transport
  - Military operations
- **Dust storm research topics**
  - Dust characteristic
  - Dust sources
  - Transport process
  - Dust forecasting

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# Trajectory Calculation

$$x_i(t + \Delta t) = x_i(t) + v_i(t) \Delta t \quad \text{where } i=1,2,3$$

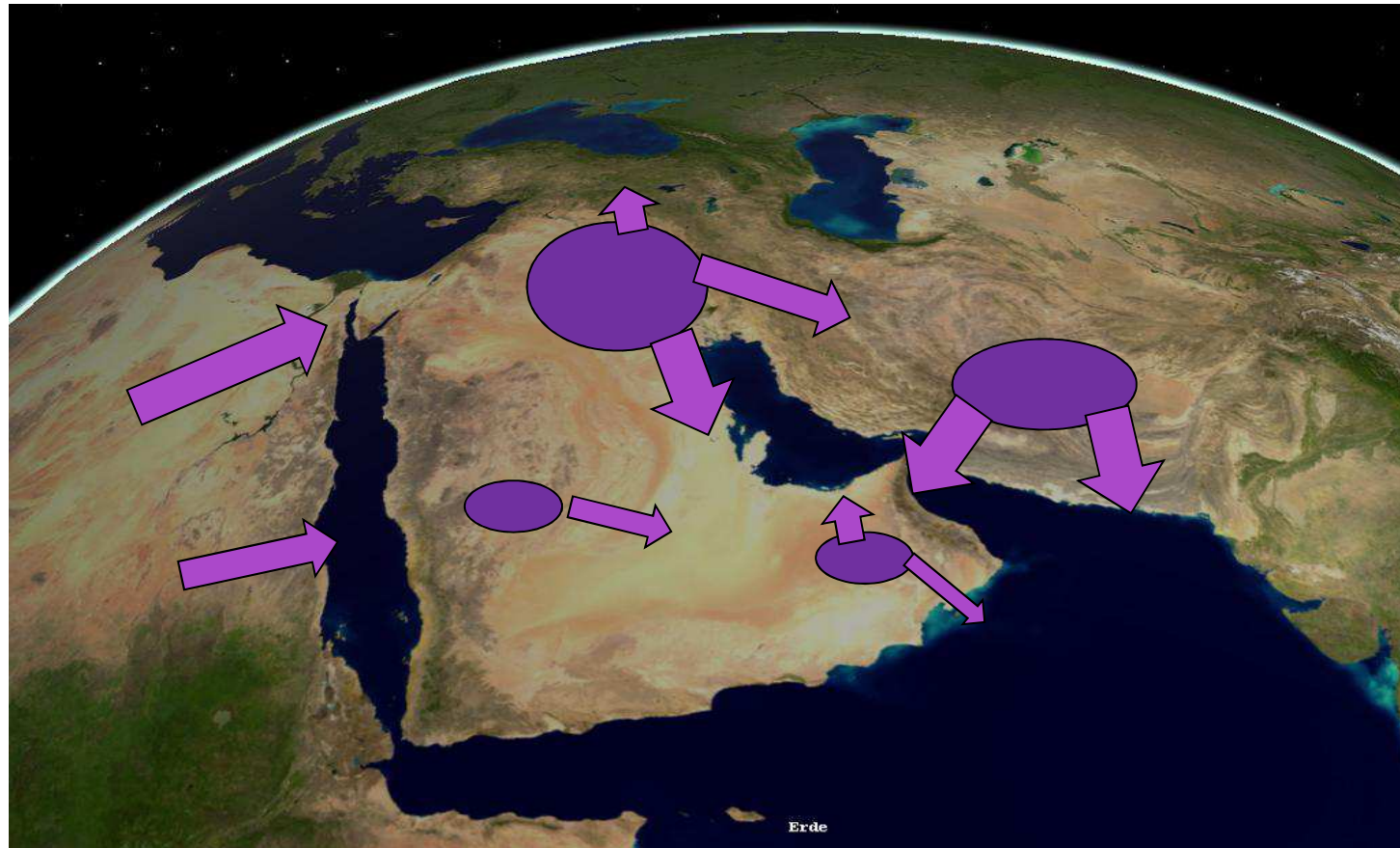
$$x_i^{n+1}(t + \Delta t) \approx x_i(t) + 0.5\Delta t \{v_i(x_i(t), t) + v_i(x_i^n(t + \Delta t), t + \Delta t)\}$$


Euler-Cauchy -Method with iteration, 2<sup>nd</sup> order accuracy

- hourly input of wind data
- cubic spatial interpolation
- linear temporal interpolation



# Dust sources surrounding the area



Dust sources surrounding the Arabian Peninsula [Al-Badi, 2006]

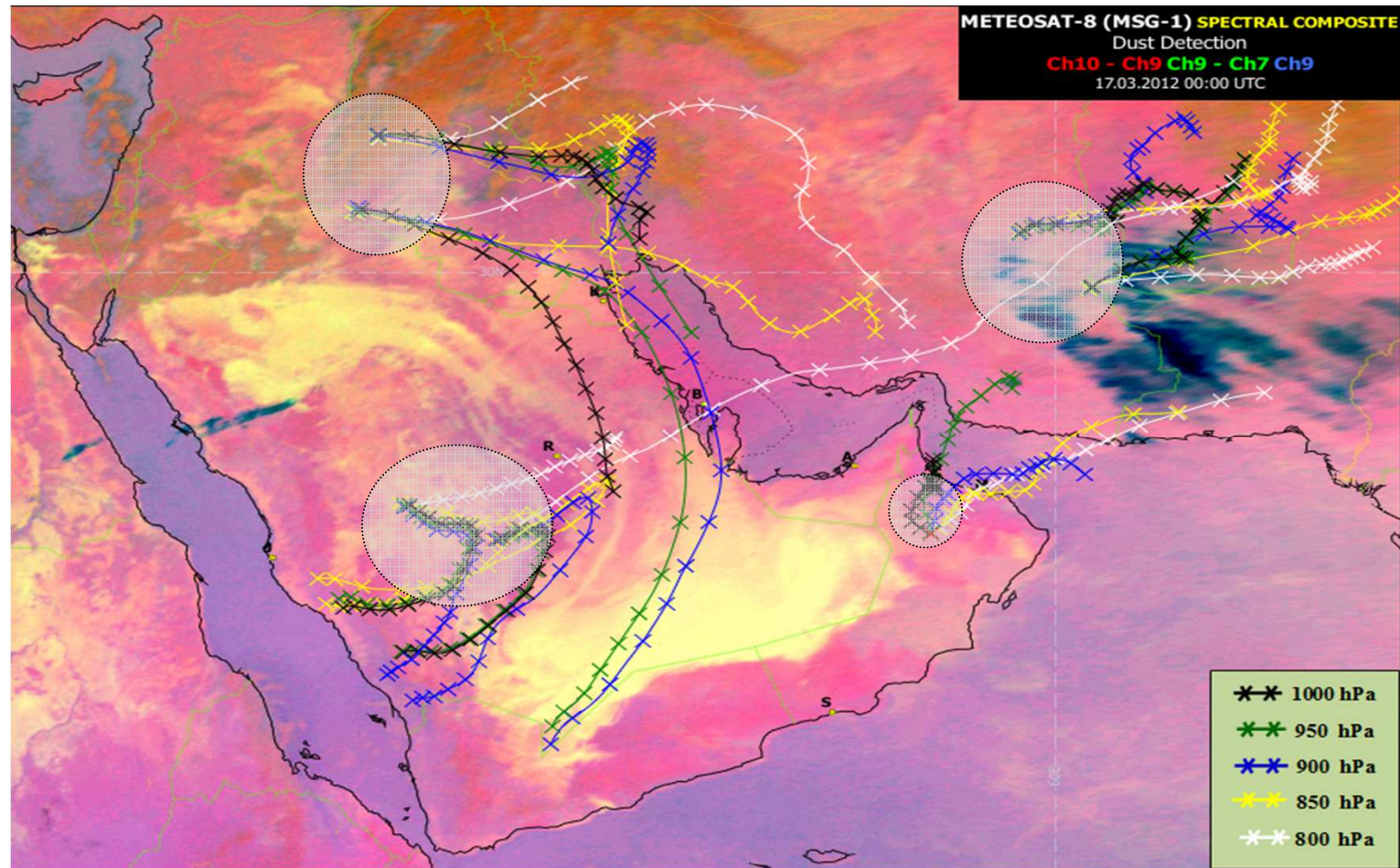


# Proposed System

- “if Scenario” mode (during normal condition)
  - Answer the question “what are the possible paths if a dust storm is generated from one of the sources?”
  - Trajectory is calculated for each dust source after each NWP model run and for different time
- “real time” mode (during dust storm condition)
  - Used to adjust the first guise of the “if scenario” mode.
  - Trajectories are recalculated after dust detection with the correct location



# 48h forecast “if scenario” for 17/3/2012 00 UTC





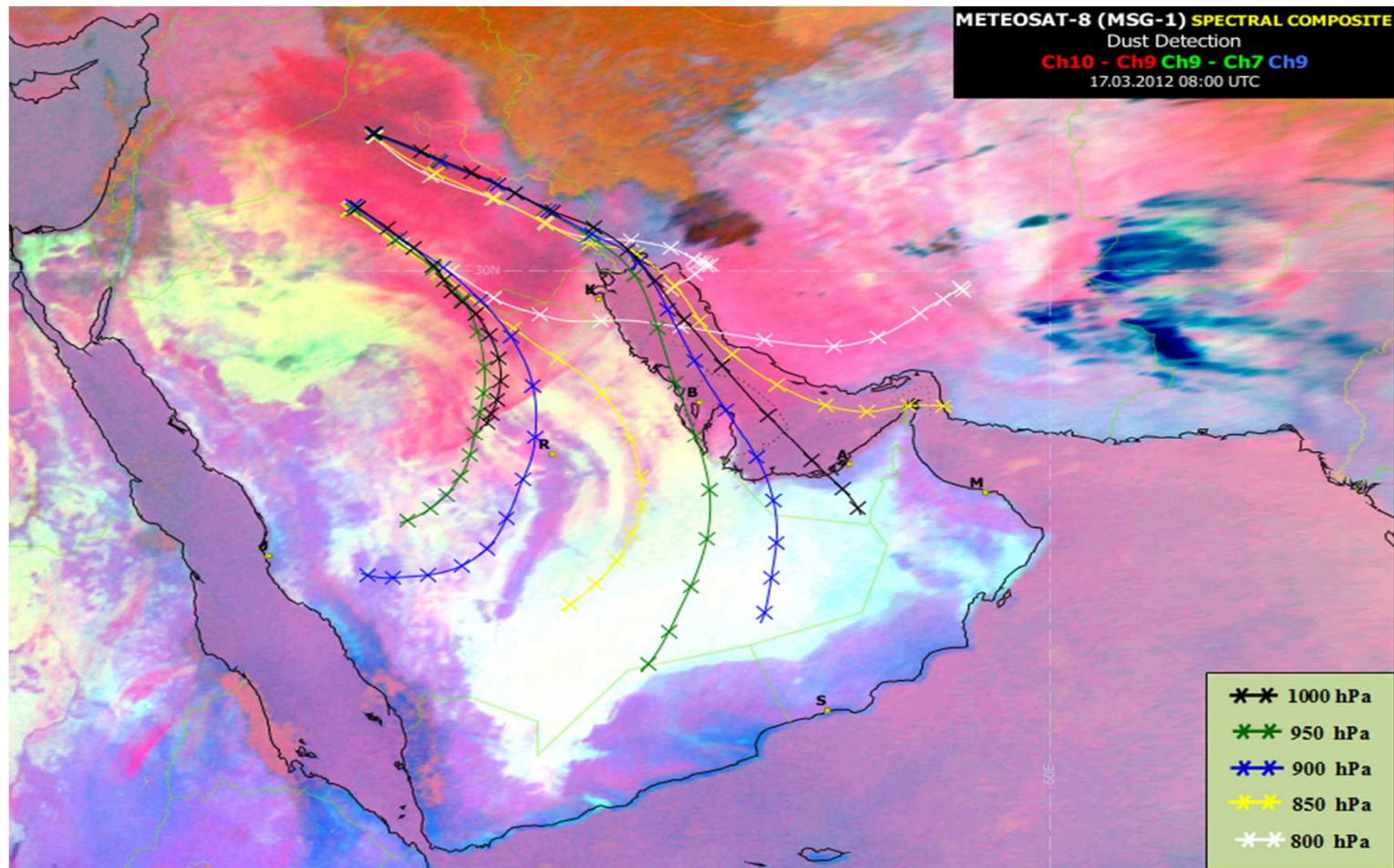
## Dust Storm 17-19 Mar 2012

### Tigris and Euphrates rivers basin



Sat: 17/3/2012 08UTC

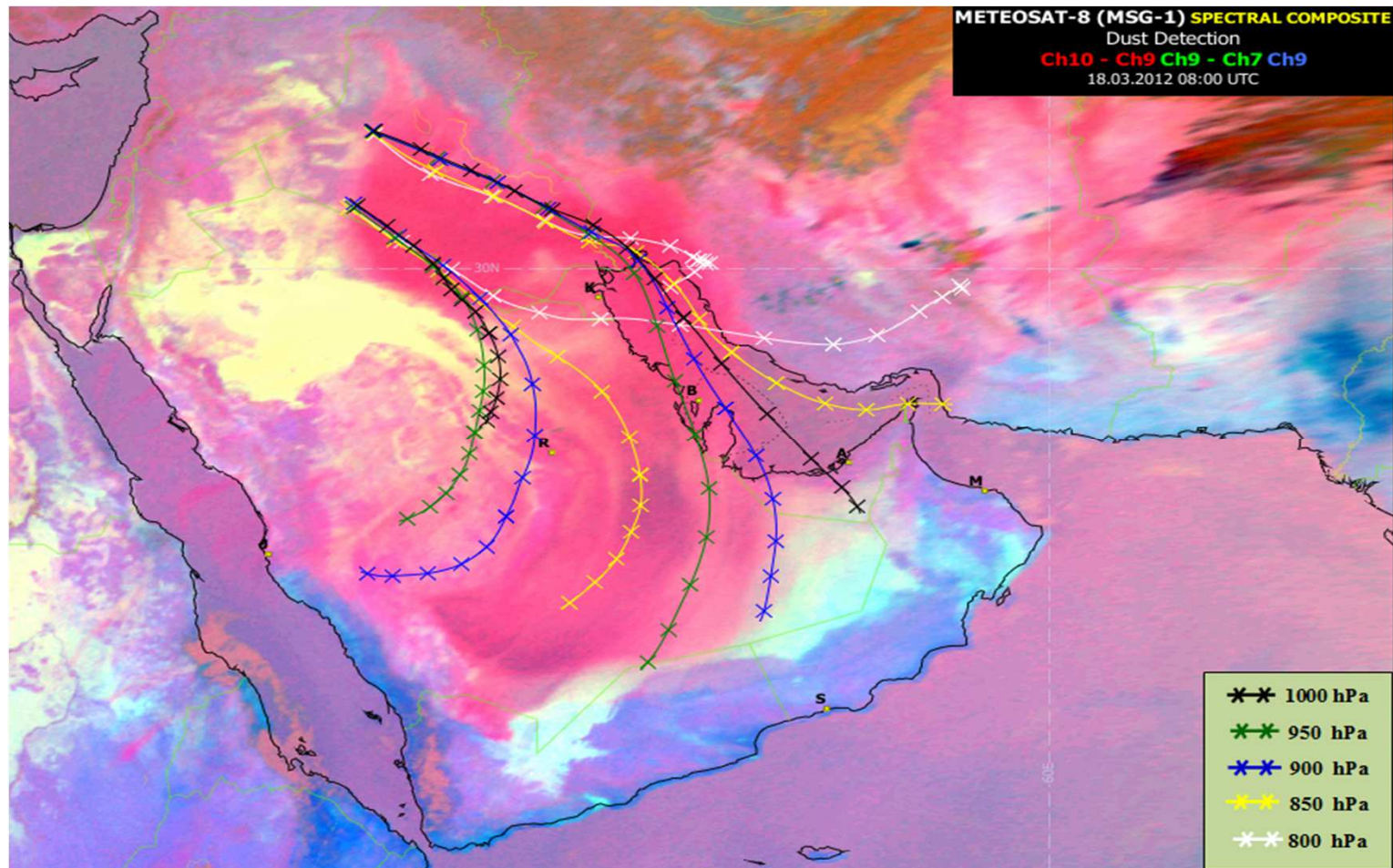
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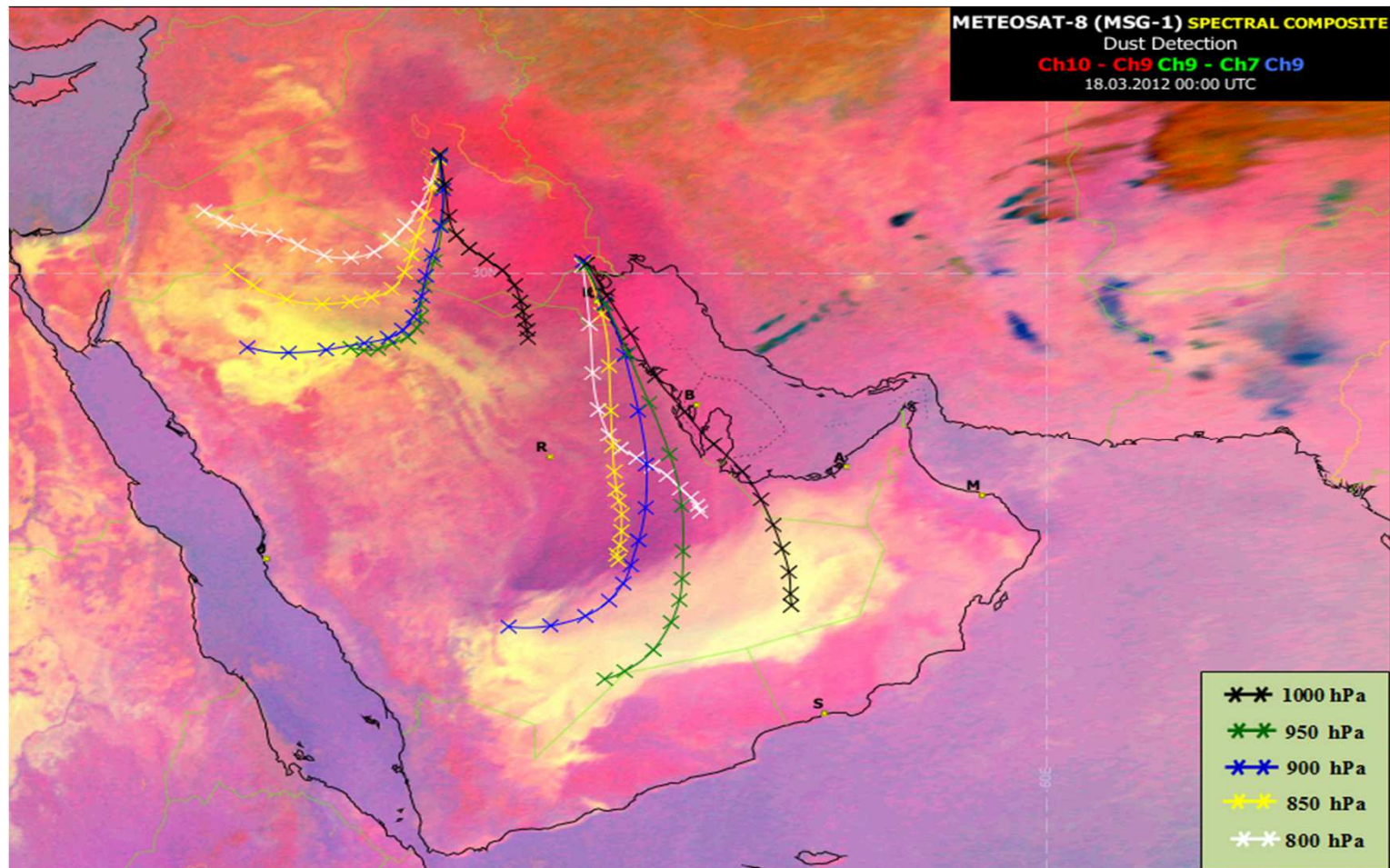
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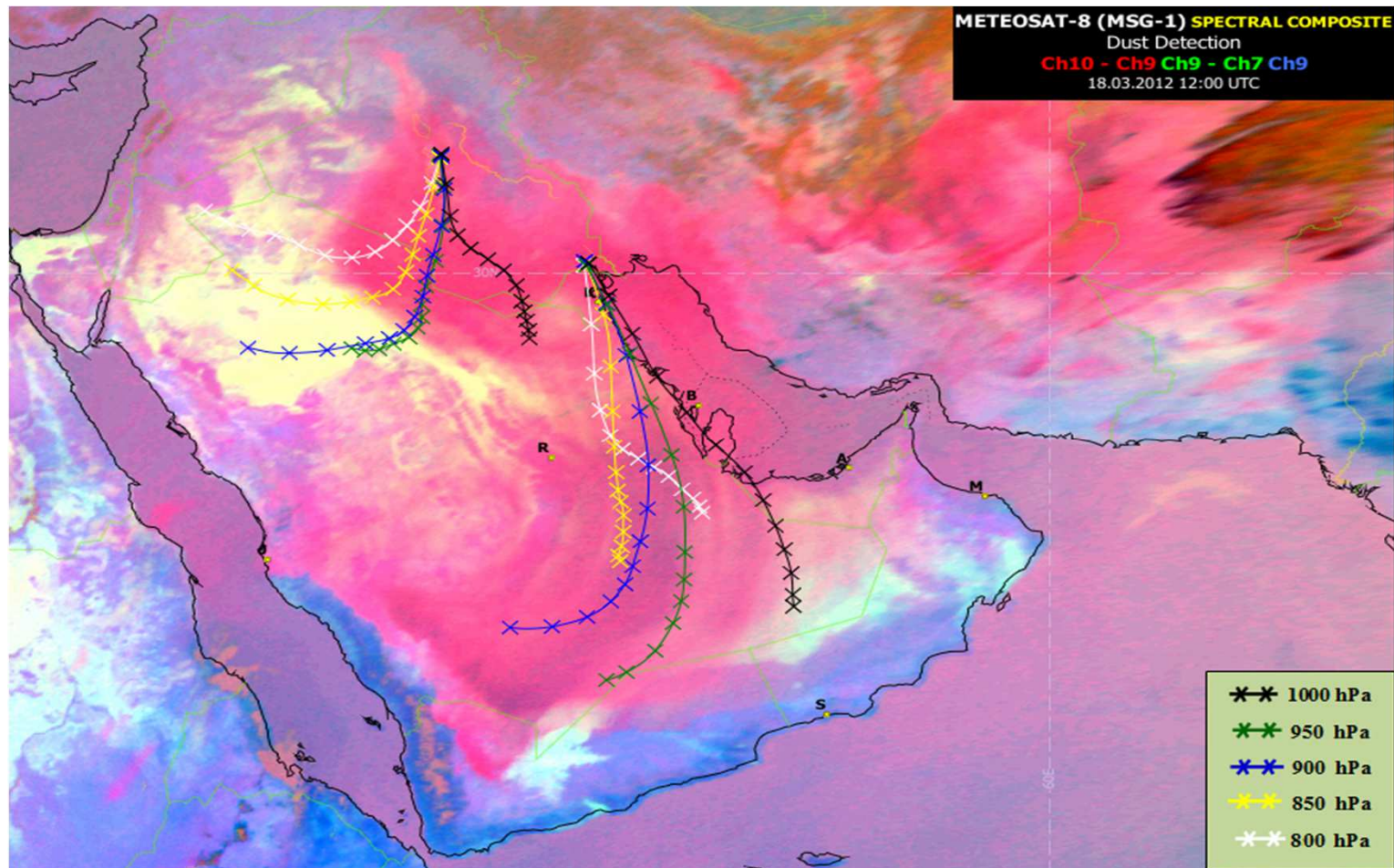
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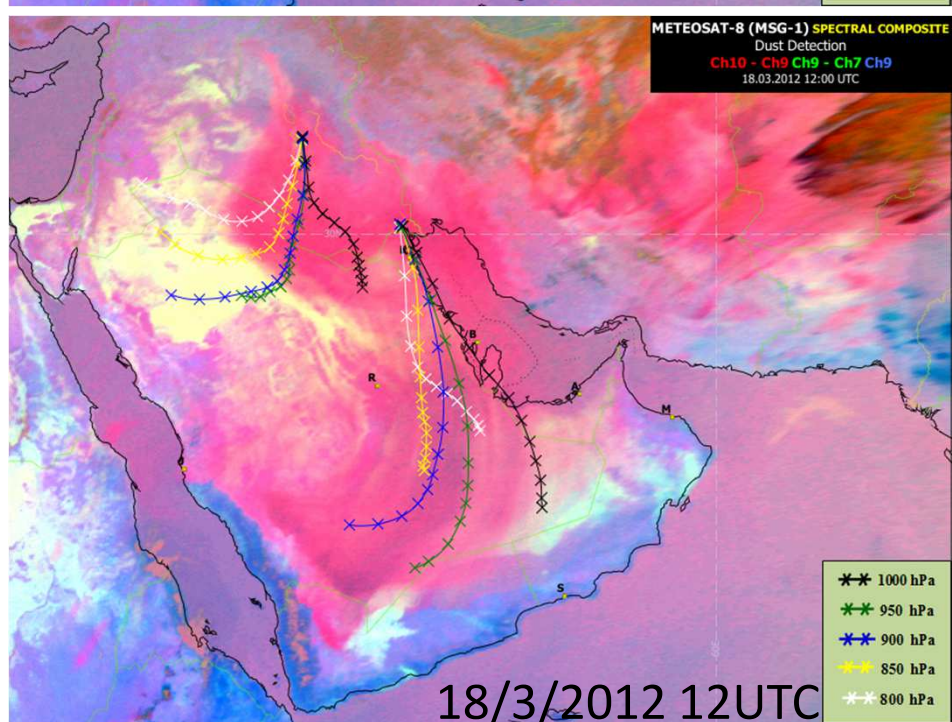
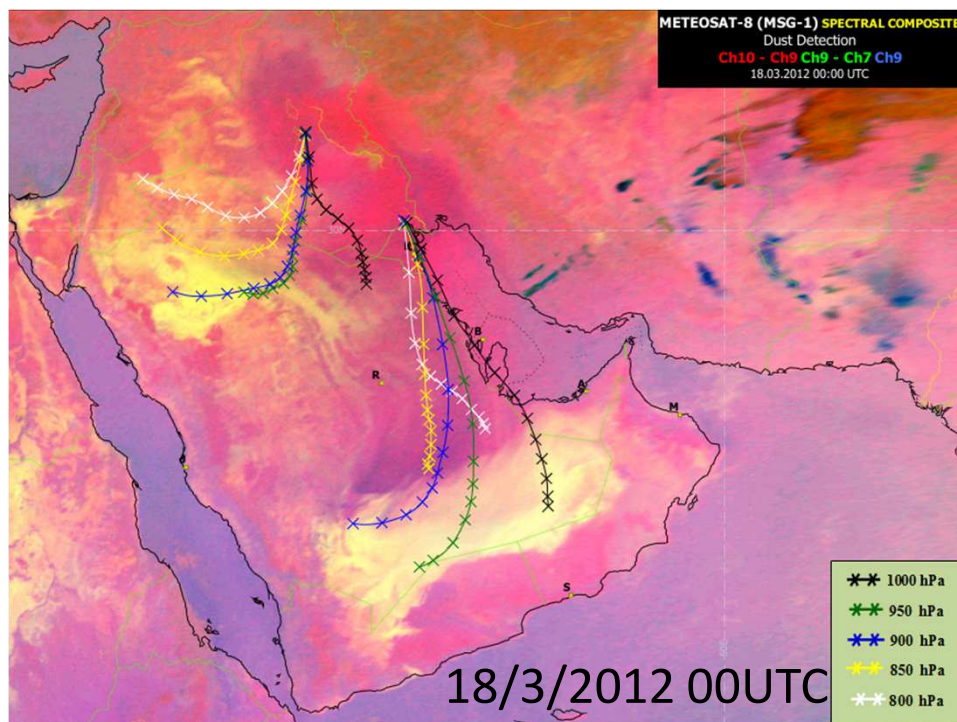
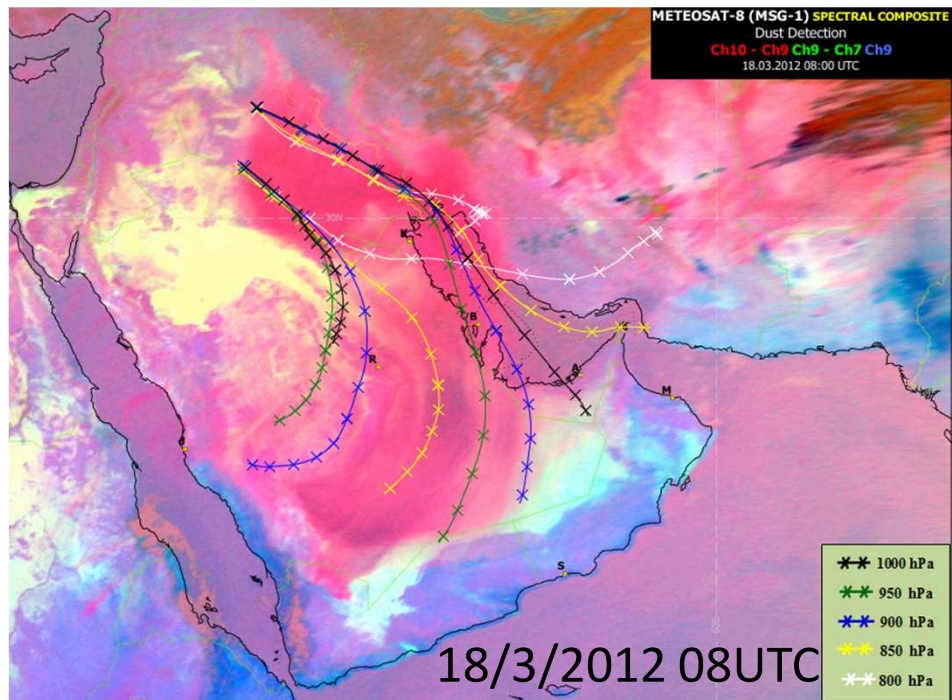
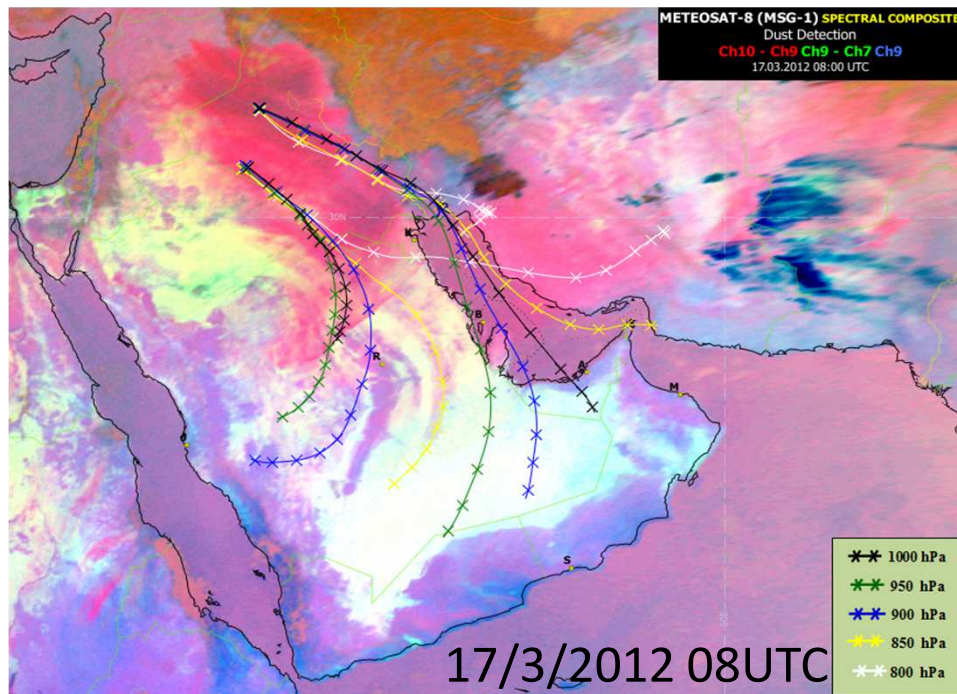


Sat: 18/3/2012 12UTC

Trajectory: 48h based on 18/3/2012 00UTC









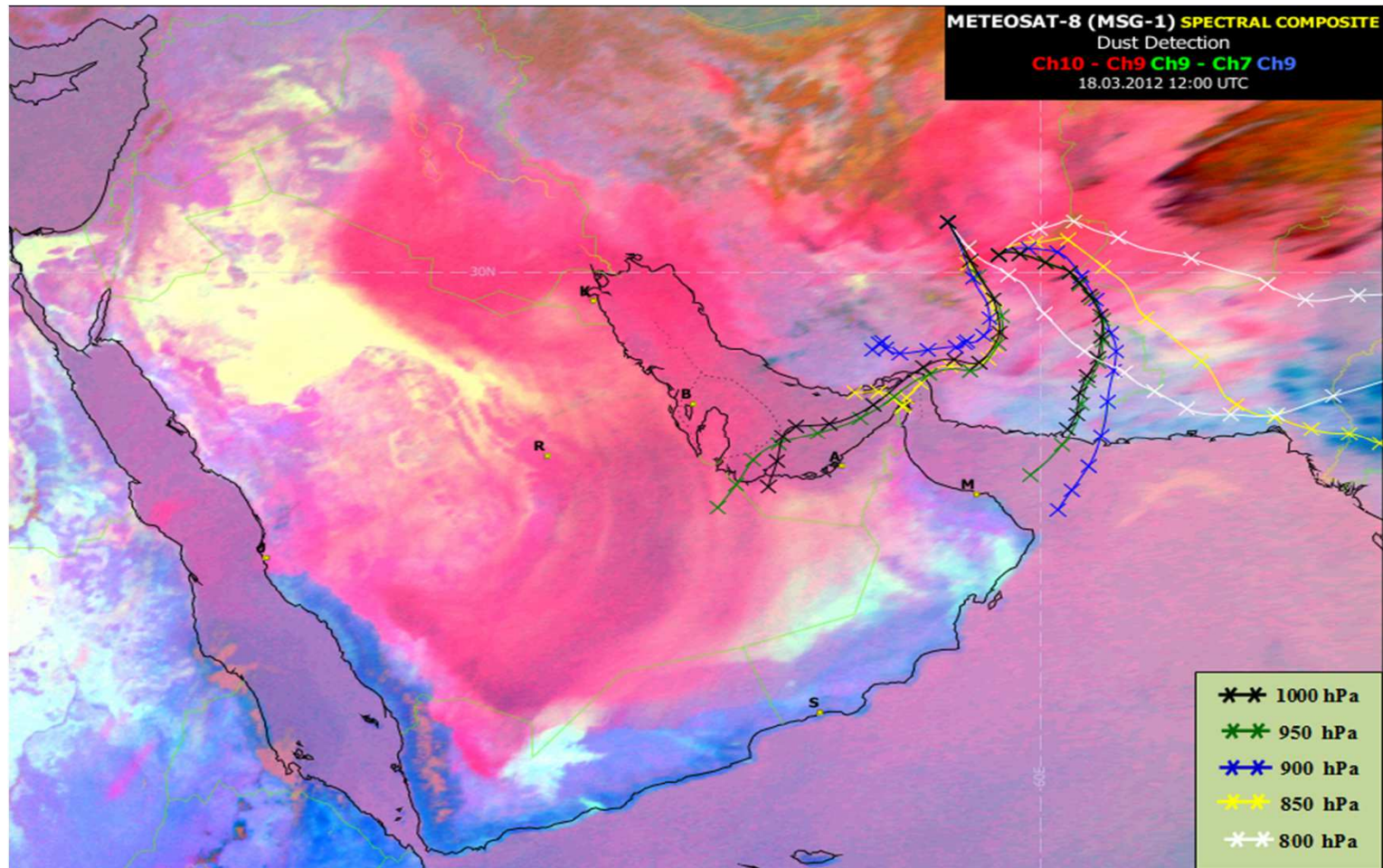


# Dust Storm 18-21 Mar 2012

## Sistan and Balouchistan basin

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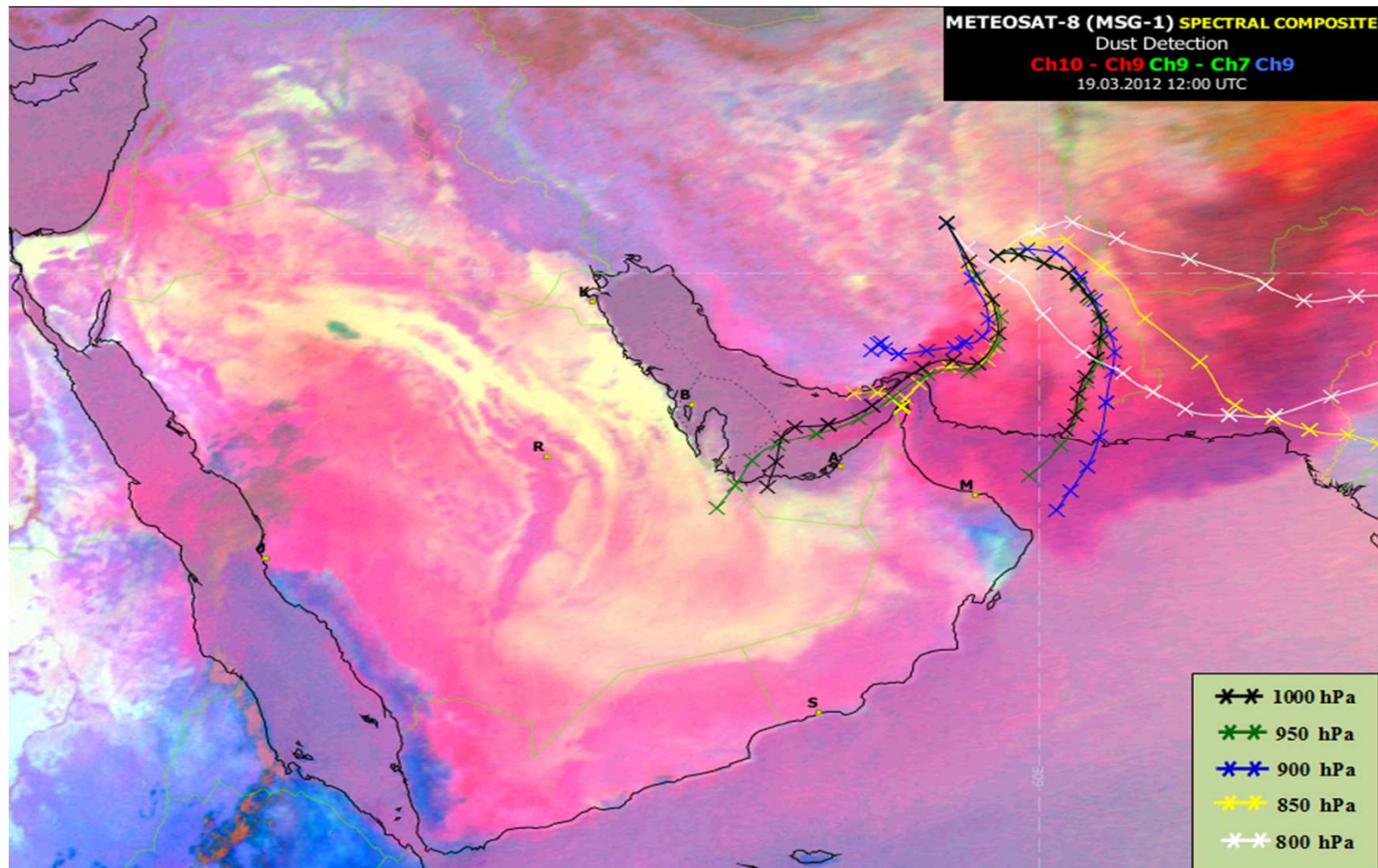
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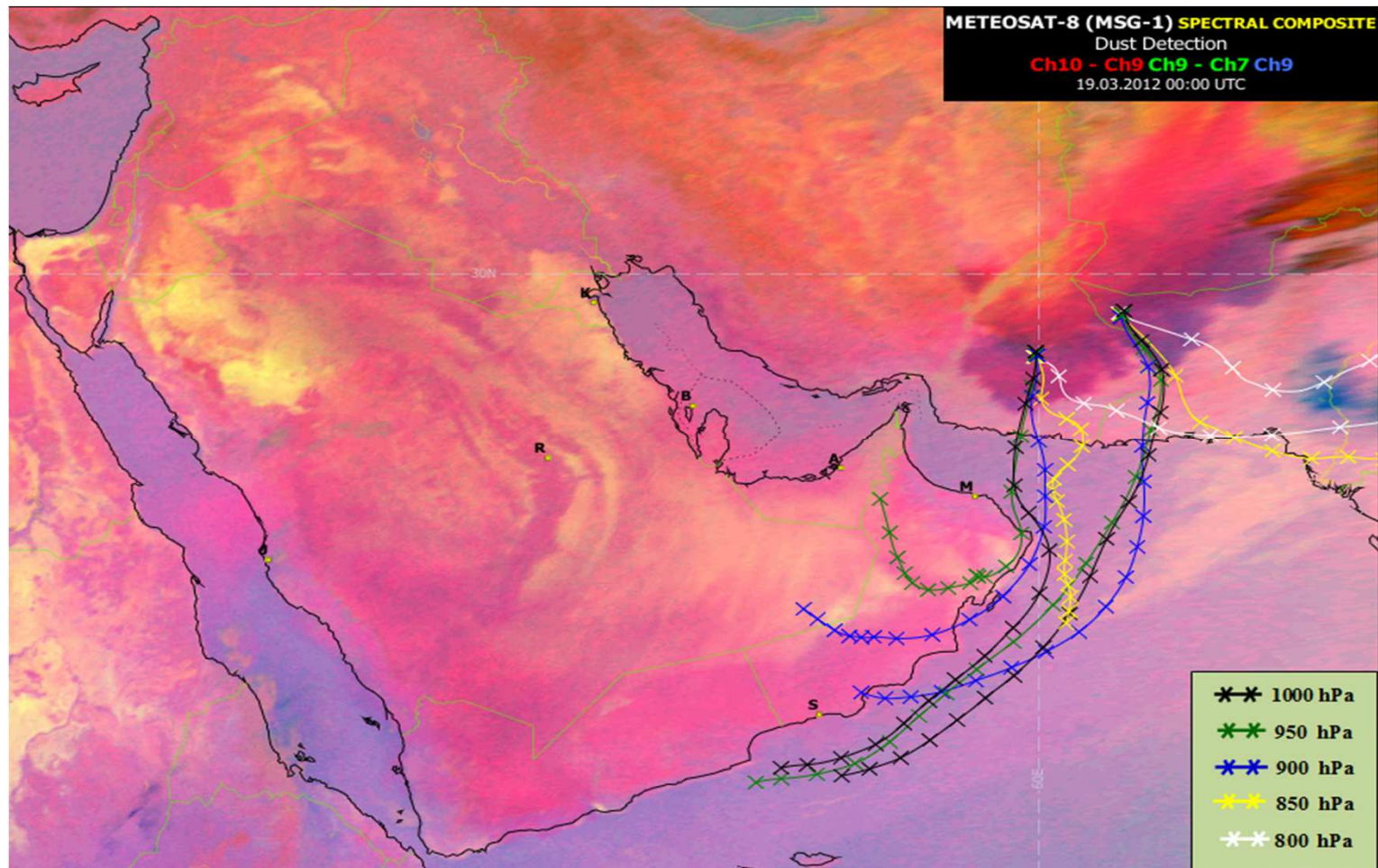
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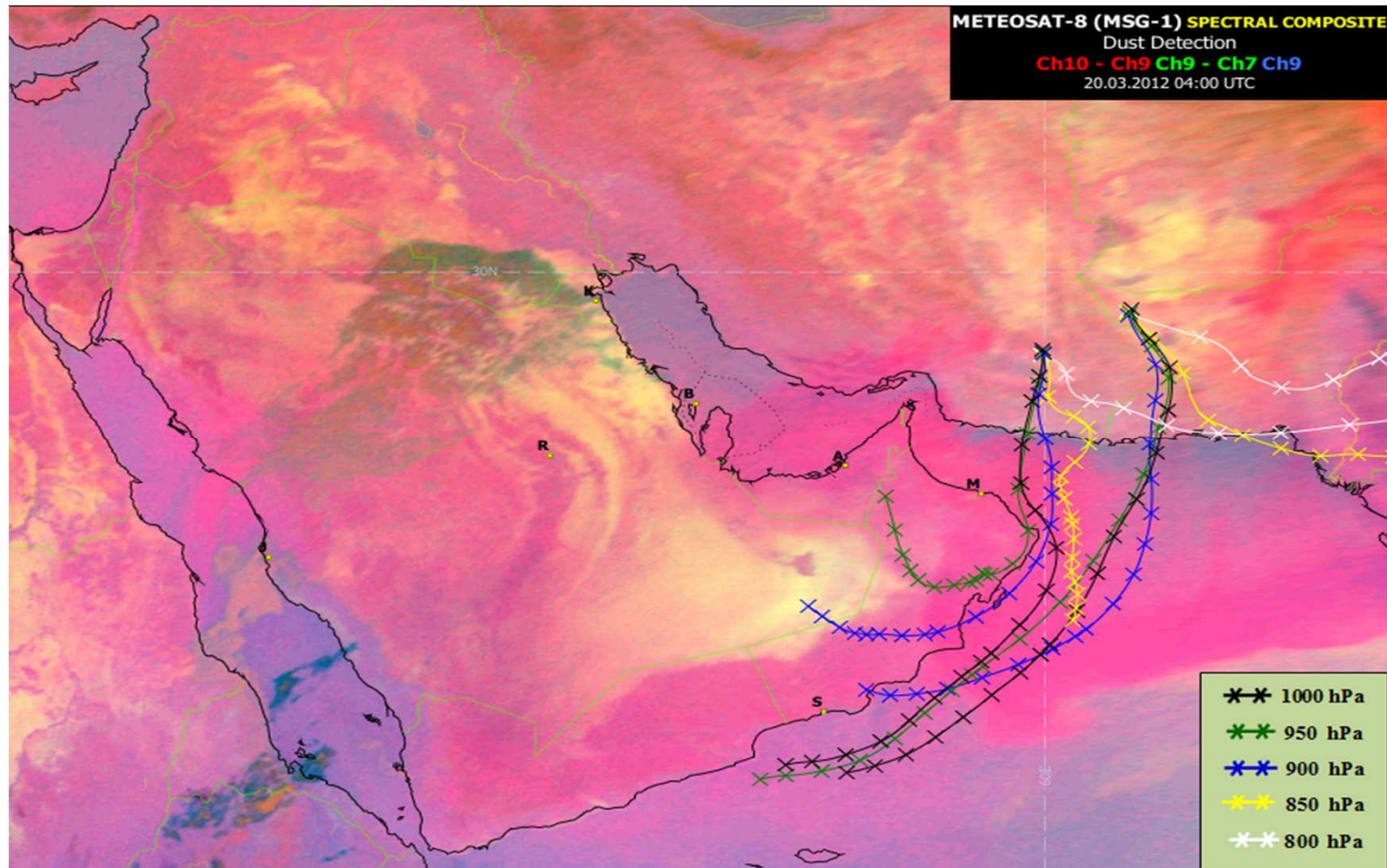
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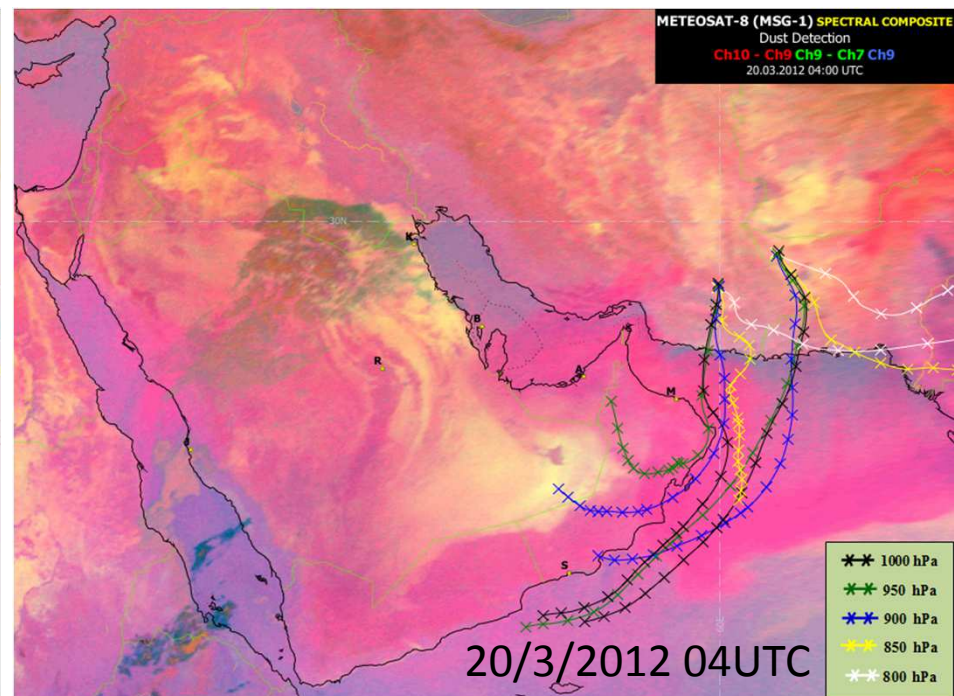
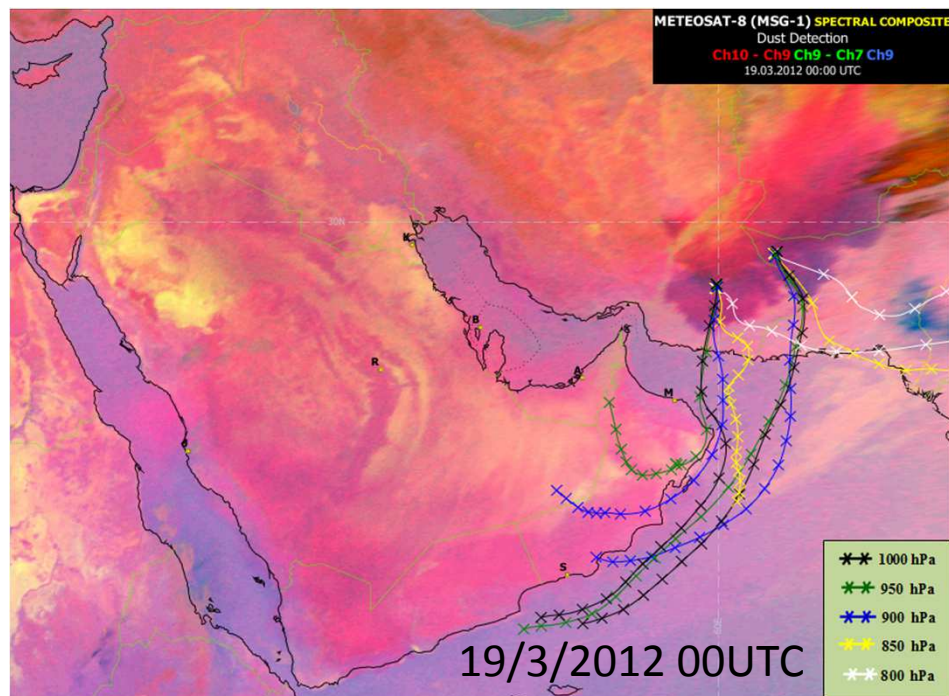
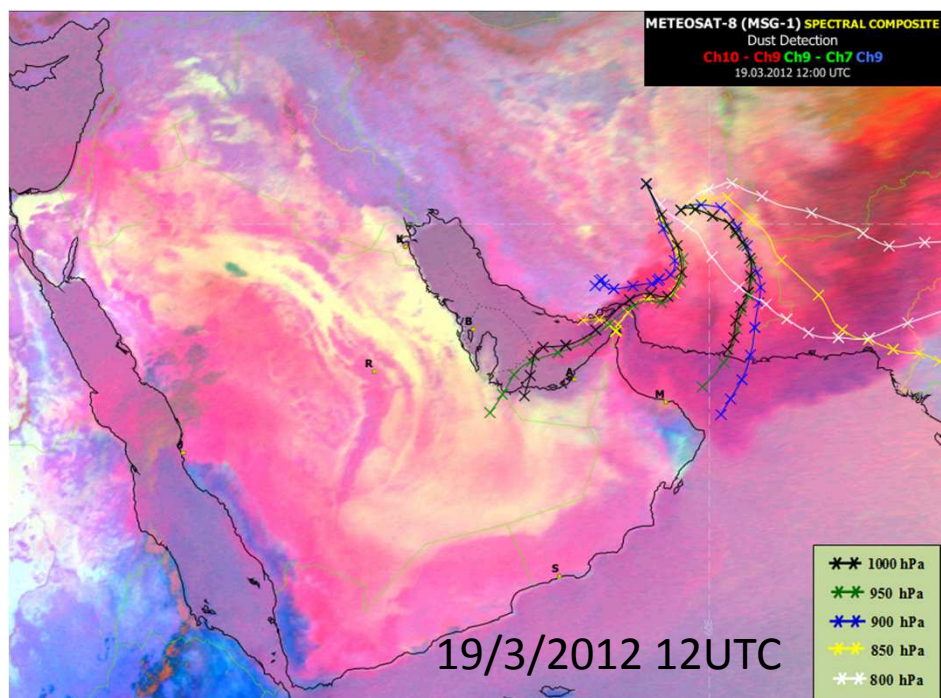
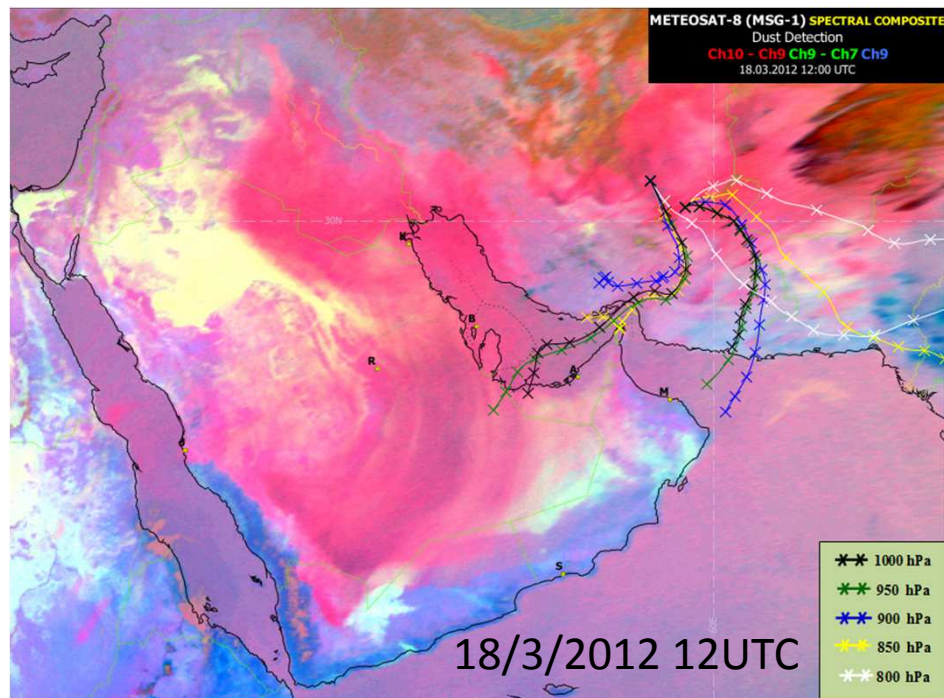


Sat: 20/3/2012 04UTC

Trajectory: 48h based on 19/3/2012 00UTC











# Conclusions

- Trajectory based forecast supporting system was proposed
- The system give a first guess guidance.
- First guess is improved once the dust storm is detected
- Validation results shows good agreement with observation
- The quality of the system is a function of the quality of the NWP model forecast



**Thank you for your  
attention**